Caution for handling the Magnetostrictive Sensor Built-in Type

What is a magnetostrictive sensor cylinder ?

By fitting existing cylinders with a magnetostrictive sensor, as opposed to a sleeve sensor, it has been possible to reduce overall cylinder length and to adjust the outlet orientation of the cord at 360°. Moreover, water-resistance is also improved and costs can be reduced since a controller can be applied at the same stroke.



Repeating accuracy	0.05 mm or less		
Temperature characteristics	±200ppmFS/°C * 1		
Output	1 ~ 5V(DC)		
Scanning frequency	Approx. 1 kHz		
Pressure proof	35MPa(Sensor rod part)		
Operating temperature range	Probe $-5^{\circ}C \sim +100^{\circ}C$		
Operating temperature range	Controller 0°C ~ +60°C		
Range of storage temperatures	Probe $-40^{\circ}C \sim +100^{\circ}C$		
hange of storage temperatures	Controller $-40^{\circ}C \sim +80^{\circ}C$		
Quake-proof	6G (or 40 Hz 2 mmpp)		
Crash-proof	50G		
Protection standard	IP67		
Probe cable	Black ø3.9 shielded cable 0.216 mm ²		
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Diagram of magnetostrictive sensor's overall dimensions



Caution for handling the Magnetostrictive Sensor

1. Outline

Magnetostrictive sensors are displacement sensors for industrial use which take advantage of magnetostrictive phenomena. They make it possible to know the absolute position of a piston moving along the sensor probe. The position of the piston is measured by measuring the propagation time of the twisting strain occurring on a special magnetostrictive wire inside the rod of the probe. 2. Connection

Place the cable from the probe after the controller as shown in the sequential table below.

Terminal No.	Terminal name	Connection		
1	SHLD	Probe shield line		
2	GND	Power source 0 V		
3	24V	Power source DC 24 V		
4	W	Probe white line		
5	В	Probe black line		
6	R	Probe red line		
7	COM	СОМ		
8		Current output (option)		
9	V	Voltage output (intra-COM output)		

st The COM and GND terminals have been sequentially placed in the internal controller.

Specifications for the controller phase connector

Lead wire strip length : 7 mm Connecting lead cable diameter : 0.2 ~ 2.5 mm² Screw tightening torque : 0.5 ~ 0.6 Nm Driver width : 3 mm Note) The connector is plugged into the controller at the factory.

Attention : please ensure that all wiring has been done correctly. (Incorrect wiring may cause malfunctioning.)

3. Zero point and gain adjustment

When output needs to be finely regulated, this can be done through the two trimmers [ZERO, GAIN] on the front of the controller. Adjustments should be performed following a warm-up period of about 15 minutes after power-up.

- Adjustment procedure (in case of 1 V ~ 5 V voltage output)
- (1) Move the cylinder to the backward limit.
- 2 Turn the [ZER0] trimmer for adjusting the zero point and adjust output to 1 V.
- ③ Move the cylinder to the forward limit.

Turn the [GAIN] trimmer for adjusting gain and adjust output.
 Output should be adjusted to the values calculated below.
 Output V={4×(Cylinder position in mm)÷(Effective length of sensor in mm)}+1
 Ex : In case of a cylinder position of 13 mm and a sensor's effective length of 15mm, output shall be 4.467 V.

- (5) Even though adjustment is completed, steps (1) through (4) should be repeated just in case.
- Note) the full-scale point (forward limit) must be adjusted only after the zero point (backward limit) has been previously adjusted.

4. Caution on handling

- When handling the probe, special care should be taken not to pull the probe cable too strongly as this may cause disconnection. In particular, remove the probe from the cylinder and pay special attention not to twist the cable if this is already attached. (Screw the probe and the cable onto the cylinder while turning them together.)
- (2) Remove the probe from the cylinder and, when screwed in, reliably fix in place with a wrench the probe head section for the width across flat (34 mm) shown in figure A below. Special care should be taken not to turn only the width across flat shown in figure B, as this may result in malfunctioning.
- ③ After mounting the probe onto the cylinder, if changing the output direction of the cable, always turn the width across flat shown in figure B after loosening the 2 screws (M3) which fix the direction of the probe head section's cord. After the output direction of the cable has been determined, tighten the two screws which fix the direction of the cord while pressing the end face of the probe head in the direction of the probe tip.
- (4) If wishing to change the combination of the probe and controller, re-adjustment is required. When combining items with different serial numbers, re-adjustment of zero point and gain is required.
- 5 For magnets, please use designated magnets whose combination has been adjusted.
- 6 Since the proper torque value for installing the magnetostrictive sensor onto the cylinder body is set at 49.0 N/m (5.0 kgf/m), keep this in mind when performing this operation.
- Please refrain from peeling off the seal either.



Caution for handling the Magnetostrictive Sensor Built-in Type



DIN rail dimension table for controller







What is a sleeve sensor cylinder ?

Sleeve sensor cylinders are existing cylinders which have been fitted with a sleeve sensor, thus making the cylinder section extremely compact in comparison with conventional limit switches. Moreover, since the sensor and the operating unit are separated, by using the comparator (sold separately) it will be possible to perform adjustments at a distance from the cylinder. Finally, repeating accuracy is extremely high at within 0.05 mm, and it is not affected by magnetic fields nor vibrations.



Comparator (sold separately)

Repeating accuracy	0.05 mm or less				
Maximum effective length	200mm				
Power supply voltage	DC+10 ~ 30V Ripple (P-P) : 2% or less				
Consumption current	25 m A or less				
Output voltage	+1 ~ +5V (Within effective range)				
Output linearity	± 2.0%FS	(Within effective range)			
Input impedance	Approx. 100 Ω				
Resonance frequency	800Hz (-3db)				
Temperature drift	300 ppm/°C for FS (0 ~ $+60^{\circ}$ C) (Changes in temperature of the probe alone occur at detector's constant temperature conditions)				
Insulation resistance	More than 100 MΩ By DC500 V mega tester Between probe/detector case and power source/output				
Range of usable temperature	Probe	$-10 \sim +120^{\circ}C$ (No freezing)			
	Detector	$-10 \sim +60^{\circ}$ C (No freezing)			
Range of storage temperature	$-20 \sim +70^{\circ}$ C (No freezing)				
Range of usable humidity	30 ~ 95% (No condensation)				
Range of storage humidity	25 ~ 95%RH (No condensation)				
Protection standard	Probe and connector joint part	IP-67 (IEC standard)			
	Other	IP-54 (IEC standard)			
Normal operating pressure	Oil pressure (dynamic) 20.6MPa				
Normal operating pressure	Oil pressure (static)	30.9MPa			
Hydraulic oil	General mineral oil and water glycol compound	d hydraulic oil			
Probe cable	with ϕ 3.4FEP shield	0.18mm ²			
Relay cable	with ϕ 3.4FEP shield	0.18mm ²			
In/Out cable	with ϕ 3.4FEP shield	0.18mm ²			
Maximum cable bend radius	R17mm				
	Reed line Red	DC+10 ~ 30V			
In/Out content	Reed line Black	OV			
in/out content	Reed line White	Output voltage +1 ~ +5V			
	Shield line	OV			

Outline dimension

* Please use sensors and detectors with matching serial numbers (SER.No).

* Since the proper torque value for installing the magnetostrictive sensor onto the cylinder body is set at 25.5 N/m (2.6 kgf/m), keep this in mind when performing this operation.



What is a comparator ?

Comparators convert the continuous signal output from the sensor (voltage output) into signal output of the two [forward and backward] points. By using sensor cylinders and comparators, it is possible to output forward and backward signals to the machine side.

Specifications for comparator

Input voltage range	DC+24V ± 10%				
Input current	Less than 50 m A				
Input current output format	Relay output/a, b contact point each 1				
Relay content	Rated current flow Less t	than AC 0.5A (100V) DC1A (24V)			
Operating temperature range	0 ~ 50°C				

- 1. Securely attach the sensor cylinder to the specified location where it is to be used.
- * Attention should be paid not to damage the sensor's cord, connectors, etc.
- * When fixing the cord avoid to forcibly bend it or pull it.
- 2. Connect the cord to the sensor, controller and (detector) comparator in this order.
 - st Attention should be paid not to mistake the connection direction of the detector.
 - * In order to avoid the influence of noise on the detector, this should be installed as far away as possible from power sources.
- 3. Connect the comparator to the DC24V power source.
- (If using AC100V, a separately sold power source is required.)
- 4. Verify that only one of the 3 light indicators (backward-side OUT, intermediate, forward-side IN) is on.
- 5. Make the cylinder move to back and forth several times by hydraulic or pneumatic pressure to ensure that it's operating normally. * This should initially be done at low pressure.
- 6. Place the rod in the prescribed backward-side position and slowly turn the backward-side adjustment knob (backward-side ADJ) all the way to the right.
 - * Verify that only the "intermediate" light is on at this point.
 - \ast The motion range of the backward-side adjustment knob (backward-side ADJ) is 270°.
- 7. Turn this knob slowly to the left in order to turn on the "backward-side OUT" light.
- \ast The trick to doing this consists in finely turning the knob to the left and to the right several times.
- 8. Next, place the rod in the prescribed forward-side position and turn the forward-side adjustment knob (forward-side ADJ) all the way to the right. Turn this knob slowly to the left in order to turn on the "forward-side IN" light.
 - * The motion range of the forward-side adjustment knob (forward-side ADJ) is 270°.
 - * If two or more lights (backward-side OUT, intermediate, forward-side IN) are on, or if no light is on, this should be considered as a sign of lack of adjustment or of abnormalities.
 - In such cases, after checking once again the wiring, the connection method, etc., please contact us.
- 9. Activate the stroke of the cylinder several times and verify that the three lights (backward-side OUT, intermediate, forward-side IN) turn on sequentially in the prescribed locations. If the lights are not on in the prescribed locations, after removing the unit for inspection and maintenance, repeat the adjustment once again from step 5.



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Table of Dimensions for Accessories of Sensor Built-in Type



Option Parts Dimensional table

Specifications in the catalog are subject to change without notice due to improvements in performance and quality.

Troubleshooting for Sensor Built-in Type

Before reading: check sensor, power source and machinery carefully for cord damage, disconnections and missing parts.

Check list when mounting

Symptom	Cause	Check/Action
None of the comparator's confirmation lights are on.	The comparator is probably not connected —> to the power source.	Ensure that DC24V is being supplied to terminals 1 and 2.
Two of the comparator's confirmation lights are on. (Backward side, forward side)	The output positions of the backward side and the forward side are probably overlapping.	Turn the backward-side adjustment knob all the way to the right; alternatively, turn the forward-side adjustment knob all the way to the right.
The power supply light of the DC24 V power supply is not on.	\longrightarrow AC100V is probably not \longrightarrow being supplied.	Verify that the power supply (outlet) is properly connected.

Check list when using the comparator

Symptom	Cause		Check/Action
The backward-side confirmation light is not on.	The adjusted output ————————————————————————————————————	->	Turn the backward-side adjustment knob slightly to the left (counter-clockwise).
The forward-side confirmation light is not on.	The adjusted output ————————————————————————————————————	->	Turn the forward-side adjustment knob slightly to the left (counter-clockwise).
The light does not come on even after turning the knob.	The detector has probably been attached in a reversed position. (When using the sleeve sensor)	->	Verify the position of the detector. (See the separate drawing).
	DC15V is probably not being supplied to the sensor.	->	Measure the voltage of terminals 3 and 4 and verify that it's DC + 15V.
	The sensor's output is probably not reaching the comparator.	>	Measure the voltage of terminals 4 and 5. Verify that the output is as per the attached table.
Relay output does not properly come through. (Light is on)	The passage of current in the relay output cord is probably interrupted.	->	Verify that the cord is properly connected and that conduction is taking place.

st In case correct functioning cannot be restored even by performing the above operations, please contact us.

Troubleshooting for Sensor

Theoretical output table for Sensor Built-in Type

Effective length of sensor	Cylinder's stroke mm	Output of forward limit V	Output of backward limit V	
	5	2.3		
15	10	3.7	1.0	
	15	5.0		
	20	3.7		
30	25	4.3	1.0	
	30	5.0		
	35	3.8		
50	40	4.2	1.0	
50	45	4.6		
	50	5.0		
	60	4.2		
76	65	4.5	1.0	
75	70	4.7	- 1.0	
	75	5.0	-	
	60	3.4		
	70	3.8	-	
100	80	4.2	1.0	
	90	4.6	-	
	100	5.0	-	
	105	4.4		
	110	4.5	-	
125	115	4.7	1.0	
	120	4.8	-	
	125	5.0	-	
	130	4.5		
	135	4.6	-	
150	140	4.7	1.0	
	145	4.9	-	
	150	5.0	-	
	155	4.5		
	160	4.6		
175	165	4.8	1.0	
	170	4.9		
	175	5.0		
	180	4.6		
	185	4.7	-	
200	190	4.8	1.0	
	195	4.9	1	
	200	5.0	-	

st This table shows approximate values and the difference with actual output is about \pm 0.2V.

 \ast Special care should be taken when handling the sleeve sensor as it may easily be damaged by sudden shocks, etc.

Squeeze monitor set

What is a squeeze monitor set ?

When employing partial pressurization (squeeze) during die casting, the quality of the product is affected by the stroke of the cylinder, which makes it necessary to check the stroke after molding.

Squeeze monitors allow to verify during molding if sensor cylinders are operating in the prescribed range (width) and make it possible to output such position to the machine side.

Also, they make it possible to minutely check the operating status of the cylinder in conjunction with data integration software.





Squeeze monitor set

What is CAST VIEWER ?

It is a device consisting of a dedicated tablet terminal and an ADC-unit for "visualizing" as waveforms the voltage output by various sensors, like those monitoring cylinder operation, hydraulic pressure, temperature, etc. Since by using CAST VIEWER you can visualize and analyze casting conditions, it allows you to set the optimal conditions. It has 8 channels for both input and output and the waveforms of multiple sensors of different types can also be displayed at the same time. In addition, since a screen is assigned to each sensor, it is possible to check and monitor the operation of individual sensors in real time.

The saving, calling and superpositioning of the waveforms are easy to perform and, when configuring pass-fail range settings, it is possible to output a relay signal.

Features : Designed for ease of use and visualization, the CAST VIEWER can be easily operated from the touch panel screen without the need of consulting the operating manual.

- * Measurement conditions are easy to set.
- * You can select only the waveform you want to visualize and easily perform superposition.
- * A different color is assigned to each waveform making them easy to distinguish. The print screen function makes it very convenient to create materials.
- * It is possible to isolate minimum, maximum and average values for effective data analysis.



- Flow control valve
- K thermocouple
- Amplifier for K thermocouple (see P171)

Specifications in the catalog are subject to change without notice due to improvements in performance and quality.

CAST VIEWER



Note) When wiring the unit, make sure to turn off the power before working.



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Specification discussion tables		Your company's na	ame :	Name of	the person in ch	narge :		
		Time and date of c	consultation :	Day	Month	Year		
Measurement items	Detaile	d measurements supplie	ed by user					
Instruments used Ch1 to ch8 (when using ch 1 as trigger, measurement will be by ch7)	☐ Cyli ☐ Cyli	inder's stroke inder's entry pressure inder's return pressure er ()	(place/s) (place/s) (place/s)	□ Cyl	inder's mold tempe inder's temperature cumulator's pressur) (place/s) place/s)	
Cylinder's specifications	🗆 Cyli	nufacturing No : () inder model : (h sensor : Yes / No	Number of units : Sensor Ty	() □ Stro pe: A / G	oke voltage : Entry lin	nit () V / I	Return limit () V)
Selection of trigger signal	🗆 Hig	cumulator's pressure → h-speed injection signal e of mounting pipe : (•				
Pressure sensor/ extension cord, connector	🗆 Len	ssure sensor (place/ ngth of extension cord (er pressure sensors (up			ensor, gauge cock, quired longer than			
Thermocouple	🗆 K tł	nermocouple Amplifier : I nermocouple (units ension compensating lea	s) sheath outer diam			nm) non-gra ′No	ounded	
Flow control valve		pler (Manufacturer :	nting method: hydrau model n		nits) with capacity t)	o resist 20.5	i Mpa pressu	re
Die-casting machine specifications		nufacturer : (Ilic machine/Electric mad) ; Mode chine	el : ()			
Name of mold/ components								
Does the sensor cord get in the way of replacement or maintenance of mold								
Setup instructions (dispatch request of our own workers)	🗆 Inst	allation Request/ Cond	lucted in-house – Installation period	-	and date of deliver Month to Day	y (Day I Month	Month Yea (ar) days)
Location of CAST VIEWER	🗆 Inst	tallation base Yes / No	Environment of plac	ce of use				

CAST VIEWER